

## IN THE CLAIMS

1. (currently amended) Method for the reconstruction of holographic images, the holographic image being ~~detected~~ detected by an image detection device, the holographic image being transformed in a digitized hologram, the digitized hologram being made of a number  $V_r$  of signal intensity values corresponding to as many elementary sub-images of "pixels" of the holographic image sampling intervals, the method comprising a first step of processing the digitized hologram array, and a second step of hologram reconstruction in the complex plane starting from the digitized hologram processed in the first step, the method being characterised in that the second step is carried out through discrete Fresnel transform starting from an array of  $V_e$  values, comprising said  $V_r$  values and an integer number  $p=V_e-V_r>$  of constant values equal to  $OS$ , corresponding to as many pixels of sizes equal to the ones of the others.
2. (currently amended) Method according to claim 1, characterised characterized in that said  $p$  constant values are null b]values ( $OS=0$ ).
3. (currently amended) Method according to claim 1, characterized in that said  $p$  values are arranged externally to said array of  $V_r$  values.
4. (original;) Method according to claim 3, characterized in that said  $p$  values are arranged in a symmetrical way.
5. (original) Method according to claim 3, characterized in that said  $p$  values are arranged in a non-symmetrical way.
6. (currently amended) Method according to ~~any one of~~ claim[[s]] 1 [[to 5]], characterized in that said number  $V_e$  of values is inversely proportional to the desired pixel size to be obtained for the reconstructed image.
7. (currently amended) Method according to ~~any one of the preceding~~ claim 1 [[s]], characterised characterized in that the digitized hologram is a square array of  $V_r=N_rM_r$  values, each value corresponding to a square pixel of sizes  $\Delta x, \Delta y$ .
8. (currently amended) Method according to claim 7, characterised characterized in that the hologram reconstructed in the second step is represented by a square array of  $V_e=N_eM_e$  values, each value corresponding to a square pixel of sizes  $\Delta\xi = (\lambda d/N_e\Delta x)$  and  $\Delta\eta = (\lambda d/M_e\Delta y)$ ,  $\lambda$  being the wavelength of the wave beam striking the object of which the hologram is recorded, and  $d$  the distance between the detection device and the object of which the hologram is detected,  $\Delta\xi$  and  $\Delta\eta$  being the reconstructed holographic image sampling intervals.
9. (original) Method according to claim 8, characterized in that  $N_e = (\lambda d/\Delta x^2)$ ,  $M_e = (\lambda d/\Delta y^2)$  ( $\Delta\xi = \Delta x$ ,  $\Delta\eta = \Delta y$ ).
10. (currently amended) Method according to ~~any one of the preceding~~ claim[[s]] 1, characterised characterized in that, after the second step, if each holographic image

sampling interval is not equal or less than a certain threshold, the number of values p added to the digitized hologram array is increased and the second step is carried out again.

11. (currently amended) Method according to claim 10, characterized in that said threshold is a function of the signal-to-noise ratio of the holographic image.
12. (currently amended) Computer program characterized in that it comprises code means apt to execute, when running on a computer, the method according to any one of claim[[s]] 1 [[to 11]].
13. (original) Memory medium, readable by a computer, storing a program, characterized in that the program is the computer program according to claim 12.
14. (currently amended) Apparatus for detection of holographic processing unit, characterized in that the processing unit processes the detected data by using the method according to any one of claim[[s]] 1 [[to 11]].